

JIM 319

Vector Calculus

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Differentiation of Scalar and Vector
Functions

Vector Functions, Limit and Derivatives

Learning Objectives

At the end of this e-lecture, students should be able to:

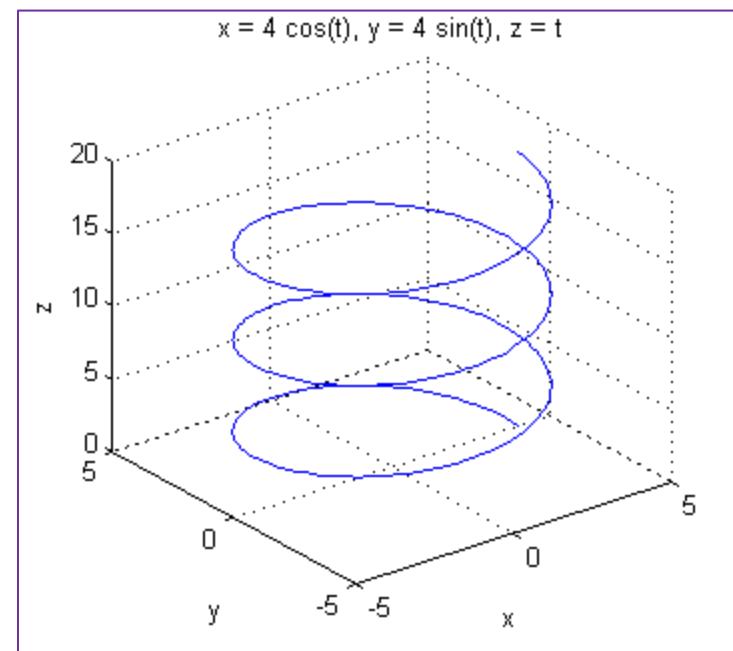
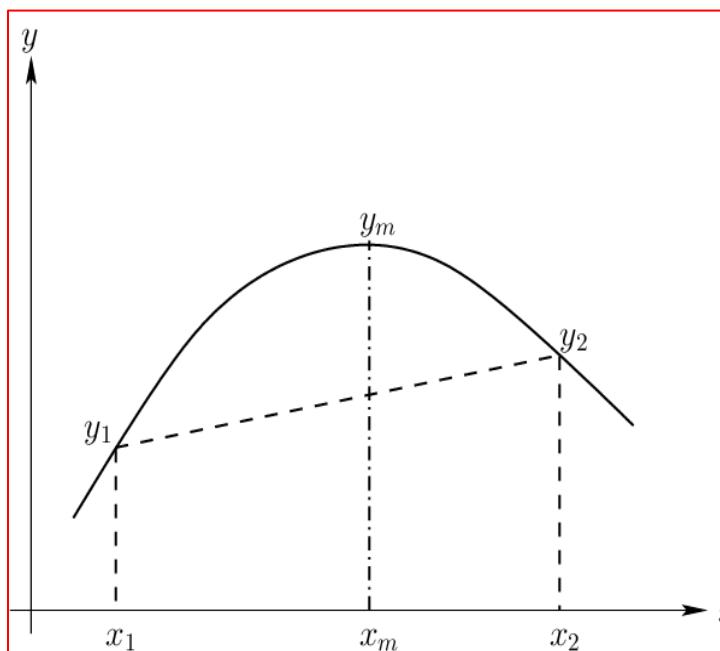
- Define the vector-valued functions and sketch space curves.**
- Understand the concept of limit and continuity of vector functions.**
- Compute the derivatives of vector functions.**
- Understand the concept and properties of derivatives.**

Introduction

- In real calculus, we are dealing with real-valued function that definitely produced the scalar quantity.
- Meanwhile, in vector calculus, most of the problem will be in the form of vector-valued function.

Introduction

- How to represent **scalar-valued function** and **vector-valued function**?



Scalar-Valued Function

- A scalar-valued function is a function that takes one or more values but returns a single value. For example,

$$f(x, y, z) = x^2 + 2yz^5$$

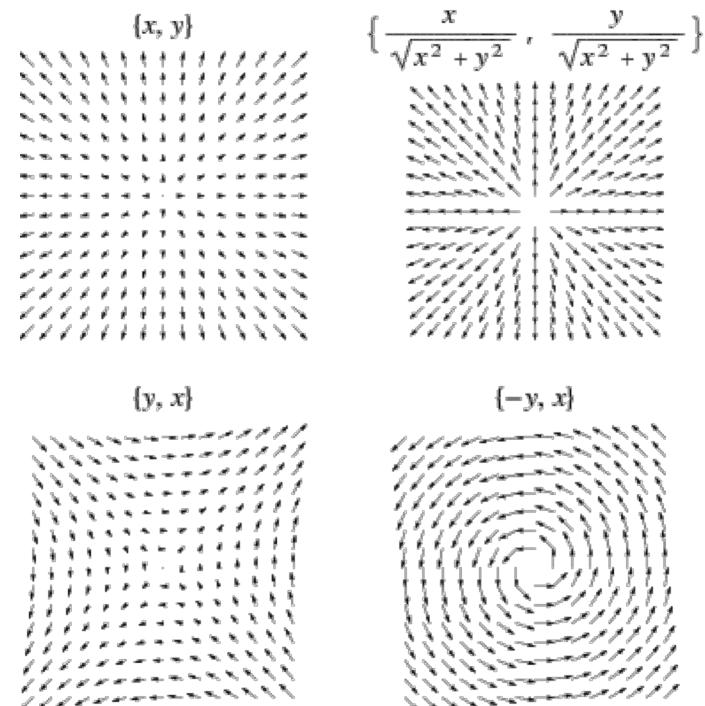
A n-variable scalar valued function acts as a map from the space \mathbf{R}^n to the real number line. That is, $f:\mathbf{R}^n \rightarrow \mathbf{R}$.

Scalar Field

- A “scalar field” is a fancy name for a function of space, i.e. it associates a real number with every position in some space, e.g. in 3D $\emptyset = \emptyset(x, y, z)$.
- Formally, scalar is a word used to distinguish the field from a vector field. If at every point in a region, a scalar function has a defined value, the region is called a **scalar field**.
- **Example:** Temperature distribution in a rod.

Vector Field

- A vector field is one where a quantity in “space” is represented by both magnitude and direction, i.e by vectors.
- Imagine rain on the mountain. The vectors are also “streamlines.” Water running down the mountain will follow these streamlines.



Vector-Valued Function

- In general, a function can be defined as a rule that assigns to each element in domain and range.
- A vector-valued function or vector function, is a function whose domain comprises of a set of real numbers and the range is a set of vectors.
- In this section, our focus will be the vector functions \underline{r} whose are \mathbb{R}^3 vectors.

Example 1

Determine the domain of the following function:

$$\underline{r} = (\cos t, \ln(4 - t), \sqrt{t + 1})$$

The first component is defined for all t's.

The second component is only defined for $t < 4$.

The third component is only defined for $t \geq -1$.

Putting all of these together gives the following domain.

$$\text{Domain of } \underline{r} = [-1, 4)$$

Example 2

Sketch the graph of each of the following vector functions.

$$\underline{r}(t) = (t, t^3 - 10t + 7)$$

Solution

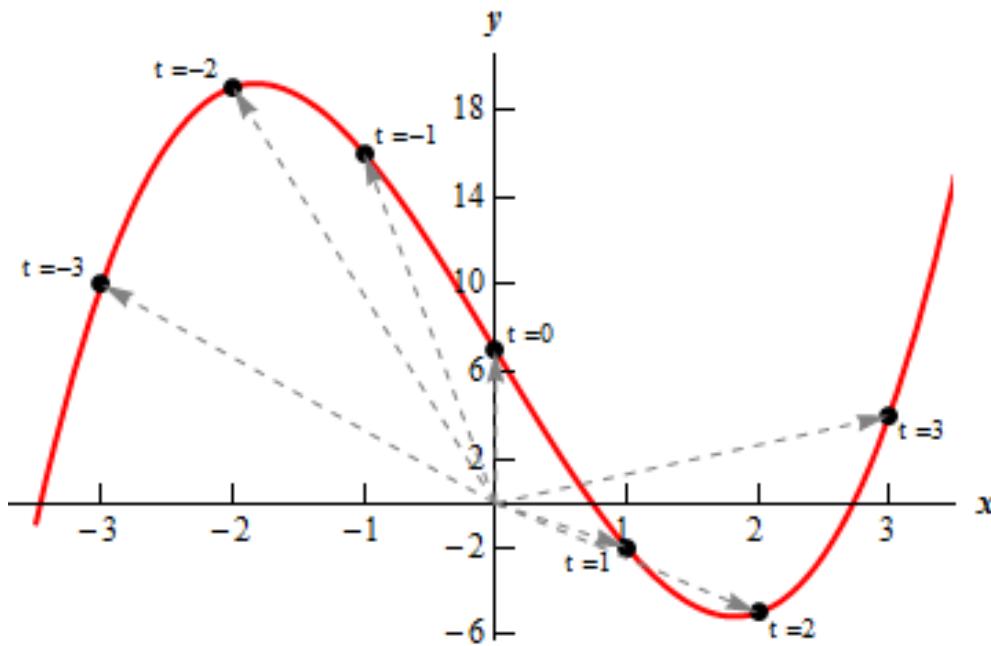
Try a few evaluation for this vector function,

$$\begin{aligned}\underline{r}(-3) &= (-3, 10), & \underline{r}(-1) &= (-1, 16) \\ \underline{r}(1) &= (1, -2), & \underline{r}(3) &= (3, 4)\end{aligned}$$

So, we've got a few points on the graph of this function. In general, it can take quite a few function evaluations to get an idea of what the graph is and it's usually easier to use a computer to do the graphing.

Example 2

Therefore, we can sketch the graph for that vector function. We've put in a few vectors/evaluations to illustrate them, but the reality is that we did have to use a computer to get a good sketch here.



Example 3

Sketch the graph of the following vector function.

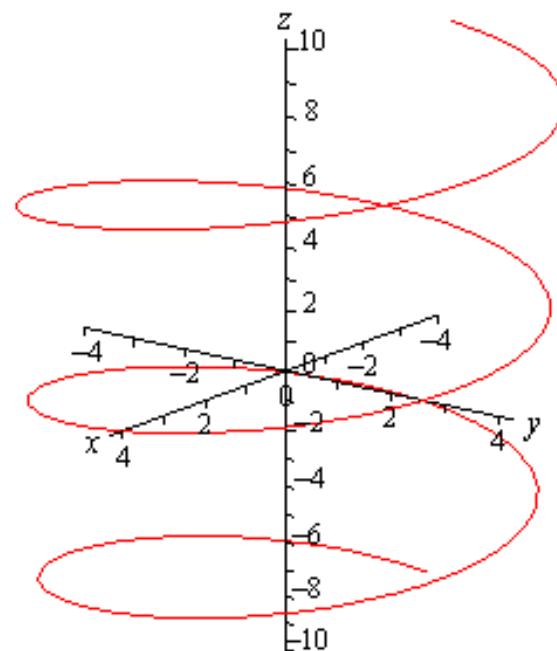
$$\underline{r}(t) = (4 \cos t, 4 \sin t, t)$$

Solution:

- If this one had a constant in the z component we would have another circle.
- However, in this case we don't have a constant. Instead we've got a t and that will change the curve.
- However, because the x and y component functions are still a circle in parametric equations our curve should have a circular nature to it in some way.

Example 3

- In fact, the only change is in the z component and as t increases the z coordinate will increase.
- Also, as t increases the x and y coordinates will continue to form a circle centered on the z -axis. Here is a sketch of this curve.



Limit and Continuity of Vector Functions

- The limit of a vector function \underline{r} is defined by taking the limits of its component functions as follows:

If $\underline{r}(t) = f(t)\underline{i} + g(t)\underline{j} + h(t)\underline{k}$, then

$$\lim_{t \rightarrow a} \underline{r}(t) = \left[\lim_{t \rightarrow a} f(t) \right] \underline{i} + \left[\lim_{t \rightarrow a} g(t) \right] \underline{j} + \left[\lim_{t \rightarrow a} h(t) \right] \underline{k}$$

provided the limits of the component function exists.

Limit and Continuity of Vector Functions

- Limits of vector functions obey the same rules as limits of real-valued functions.

Example 4

Find the $\lim_{t \rightarrow 0} \underline{r}(t) = (1 + t^3)\underline{i} + te^{-t}\underline{j} + \frac{\sin t}{t}\underline{k}$

Solution:

According to definition,

$$\begin{aligned}\lim_{t \rightarrow 0} \underline{r}(t) &= \left[\lim_{t \rightarrow 0} (1 + t^3) \right] \underline{i} + \left[\lim_{t \rightarrow 0} te^{-t} \right] \underline{j} \\ &\quad + \left[\lim_{t \rightarrow 0} \frac{\sin t}{t} \right] \underline{k} \\ &= \underline{i} + \underline{k}\end{aligned}$$

Limit and Continuity of Vector Functions

- A vector function \underline{r} is continuous at $t=a$ if
 - I. $\lim_{t \rightarrow a} \underline{r}(t)$ exists
 - II. \underline{r} is defined at a .
 - III. $\lim_{t \rightarrow a} \underline{r}(t) = \underline{r}(a)$

Derivatives of Vector Functions

- The derivatives \underline{r}' of a vector function \underline{r} is defined in the same way as for real-valued functions:
- Given the following equation:

$$\frac{d\underline{r}}{dt} = \underline{r}'(t) = \lim_{h \rightarrow 0} \frac{\underline{r}(t + h) - \underline{r}(t)}{h}$$

Example 5

Find the derivative of $\underline{r}(t) = (1 + t^3)\underline{i} + (te^{-t})\underline{j} + \sin 2t \underline{k}$. Hence, find the unit tangent vector at the point where $t = 0$.

SOLUTION:

$$\begin{aligned}\frac{d\underline{r}}{dt} &= \underline{r}'(t) = \frac{d}{dt} ((1 + t^3)\underline{i} + (te^{-t})\underline{j} + \sin 2t \underline{k}) \\ &= 3t^2 \underline{i} + (1 - t)e^{-t} \underline{j} + 2 \cos 2t \underline{k}\end{aligned}$$

Example 5

when $t = 0$.

$$\begin{aligned}\underline{r}'(t) &= 3(0)^2 \underline{i} + (1 - 0) e^{-0} \underline{j} + 2 \cos 2(0) \underline{k} \\ &= \underline{j} + 2 \underline{k}\end{aligned}$$

$$\|\underline{r}'(t)\| = \sqrt{(1)^2 + (2)^2} = \sqrt{5}$$

Unit tangent vector,

$$\underline{T} = \frac{\underline{r}'(t)}{\|\underline{r}'(t)\|} = \frac{1}{\sqrt{5}} \underline{j} + \frac{2}{\sqrt{5}} \underline{k}$$

Derivatives of Vector Functions

- Suppose \underline{A} , \underline{B} , and \underline{C} are differentiable vector function of a scalar u and ϕ is a differentiable scalar function of u . The following law hold:

LAW 1 (Addition)

$$\frac{d}{du} (\underline{A} + \underline{B}) = \frac{d\underline{A}}{du} + \frac{d\underline{B}}{du}$$

Derivatives of Vector Functions

LAW 2 (Product Rule)

$$\frac{d}{du} (\underline{A} \cdot \underline{B}) = \underline{A} \cdot \frac{d\underline{B}}{du} + \frac{d\underline{A}}{du} \cdot \underline{B}$$

LAW 3 (Cross Product)

$$\frac{d}{du} (\underline{A} \times \underline{B}) = \underline{A} \times \frac{d\underline{B}}{du} + \frac{d\underline{A}}{du} \times \underline{B}$$

LAW 4 (Product Rule)

$$\frac{d}{du} (\phi \underline{A}) = \phi \frac{d\underline{A}}{du} + \frac{d\phi}{du} \underline{A}$$

Derivatives of Vector Functions

LAW 5 (Scalar Triple Product)

$$\frac{d}{du} (\underline{A} \cdot \underline{B} \times \underline{C}) = \underline{A} \cdot \underline{B} \times \frac{d\underline{C}}{du} + \underline{A} \cdot \frac{d\underline{B}}{du} \times \underline{C} + \frac{d\underline{A}}{du} \cdot \underline{B} \times \underline{C}$$

LAW 6 (Vector Triple Product)

$$\begin{aligned} \frac{d}{du} \{\underline{A} \times (\underline{B} \times \underline{C})\} &= \underline{A} \times \left(\underline{B} \times \frac{d\underline{C}}{du} \right) + \underline{A} \times \left(\frac{d\underline{B}}{du} \times \underline{C} \right) + \\ &\quad \frac{d\underline{A}}{du} \times (\underline{B} \times \underline{C}) \end{aligned}$$

Example 6 (a)

Suppose $\underline{A} = 5u^2 \underline{i} + u \underline{j} - u^3 \underline{k}$ and $\underline{B} = \sin u \underline{i} - \cos u \underline{j}$. Find $\frac{d}{du} (\underline{A} \cdot \underline{B})$.

Solution:

$$\frac{d}{du} (\underline{A} \cdot \underline{B}) = \underline{A} \cdot \frac{d\underline{B}}{du} + \frac{d\underline{A}}{du} \cdot \underline{B}$$

$$\frac{d\underline{B}}{du} = \cos u \underline{i} + \sin u \underline{j} \quad \frac{d\underline{A}}{du} = 10u \underline{i} + \underline{j} - 3u^2 \underline{k}$$

$$= (5u^2 \underline{i} + u \underline{j} - u^3 \underline{k}) \cdot (\cos u \underline{i} + \sin u \underline{j}) + (10u \underline{i} + \underline{j} - 3u^2 \underline{k}) \cdot (\sin u \underline{i} - \cos u \underline{j})$$

$$= [5u^2 \cos u + u \sin u] + [10u \sin u - \cos u]$$

$$= (5u^2 - 1) \cos u + 11u \sin u$$

Example 6 (a)

Alternative Method:

$$\underline{A} \cdot \underline{B} = 5u^2 \sin u - u \cos u$$

$$\frac{d}{du} (\underline{A} \cdot \underline{B}) = \frac{d}{du} (5u^2 \sin u - u \cos u)$$

$$= 5u^2 \cos u + 10u \sin u + u \sin u - \cos u$$

$$= (5u^2 - 1) \cos u + 11u \sin u$$

Example 6 (b)

Find $\frac{d}{du} (\underline{A} \times \underline{B})$.

Solution:

$$\frac{d}{du} (\underline{A} \times \underline{B}) = \underline{A} \times \frac{dB}{du} + \frac{d\underline{A}}{du} \times \underline{B}$$

$$\frac{dB}{du} = \cos u \ \underline{i} + \sin u \ \underline{j}$$

$$\frac{d\underline{A}}{du} = 10u \ \underline{i} + \underline{j} - 3u^2 \underline{k}$$

$$= \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 5u^2 & u & -u^3 \\ \cos u & \sin u & 0 \end{vmatrix} + \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 10u & 1 & -3u^2 \\ \sin u & -\cos u & 0 \end{vmatrix}$$

Example 6 (b)

$$\underline{A} \times \frac{d\underline{B}}{du} + \frac{d\underline{A}}{du} \times \underline{B} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 5u^2 & u & -u^3 \\ \cos u & \sin u & 0 \end{vmatrix} + \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 10u & 1 & -3u^2 \\ \sin u & -\cos u & 0 \end{vmatrix}$$

$$= [u^3 \sin u \underline{i} - u^3 \cos u \underline{j} + (5u^2 \sin u - u \cos u) \underline{k}] + \\ [-3u^2 \cos u \underline{i} - 3u^2 \sin u \underline{j} + (-10u \cos u - \sin u) \underline{k}]$$

$$= (u^3 \sin u - 3u^2 \cos u) \underline{i} - (u^3 \cos u + 3u^2 \sin u) \underline{j} + (5u^2 \sin u - \sin u - 11u \cos u) \underline{k}$$

Example 6 (b)

Alternative Method:

$$\begin{aligned}\underline{A} \times \underline{B} &= \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 5u^2 & u & -u^3 \\ \sin u & -\cos u & 0 \end{vmatrix} \\ &= -u^3 \cos u \underline{i} - u^3 \sin u \underline{j} + (-5u^2 \cos u - u \sin u) \underline{k}\end{aligned}$$

$$\begin{aligned}\frac{d}{du}(\underline{A} \times \underline{B}) &= \frac{d}{du}(-u^3 \cos u) \underline{i} - \frac{d}{du}(u^3 \sin u) \underline{j} + \frac{d}{du}(-5u^2 \cos u - u \sin u) \underline{k} \\ &= (u^3 \sin u - 3u^2 \cos u) \underline{i} - (u^3 \cos u + 3u^2 \sin u) \underline{j} \\ &\quad + (5u^2 \sin u - \sin u - 11u \cos u) \underline{k}\end{aligned}$$

Example 6 (c)

Suppose $\underline{A} = 5u^2 \underline{i} + u \underline{j} - u^3 \underline{k}$ and $\underline{B} = \sin u \underline{i} - \cos u \underline{j}$. Find $\frac{d}{du} (\underline{A} \cdot \underline{A})$.

Solution:

$$\begin{aligned}\frac{d}{du} (\underline{A} \cdot \underline{A}) &= \underline{A} \cdot \frac{d\underline{A}}{du} + \frac{d\underline{A}}{du} \cdot \underline{A} = 2 \underline{A} \cdot \frac{d\underline{A}}{du} \\ \frac{d\underline{A}}{du} &= 10u \underline{i} + \underline{j} - 3u^2 \underline{k} \\ &= 2(5u^2 \underline{i} + u \underline{j} - u^3 \underline{k}) \cdot (10u \underline{i} + \underline{j} - 3u^2 \underline{k}) \\ &= 100u^3 + 2u + 6u^5\end{aligned}$$

Example 6 (c)

Alternative Method:

$$\underline{A} \cdot \underline{A} = (5u^2)^2 + (u)^2 + (-u^3)^2 \\ = 25u^4 + u^2 + u^6$$

$$\frac{d}{du} (\underline{A} \cdot \underline{A}) = \frac{d}{du} (25u^4 + u^2 + u^6)$$

$$= 100u^3 + 2u + 6u^5$$

Example 7 (a)-(d)

Given $\underline{R} = (3 \cos t)\underline{i} + (3 \sin t)\underline{j} + (4t)\underline{k}$.

Find:

(a) $\frac{d\underline{R}}{dt}$

(b) $\frac{d^2\underline{R}}{dt^2}$

(c) $\left\| \frac{d\underline{R}}{dt} \right\|$

(d) $\left\| \frac{d^2\underline{R}}{dt^2} \right\|$

Example 7 (a)-(d)

$$\begin{aligned}
 \text{(a)} \quad & \frac{d\underline{R}}{dt} = \frac{d}{dt}(3 \cos t) \underline{i} + \frac{d}{dt}(3 \sin t) \underline{j} + \frac{d}{dt}(4t) \underline{k} \\
 &= (-3 \sin t) \underline{i} + (3 \cos t) \underline{j} + 4 \underline{k}
 \end{aligned}$$

$$\begin{aligned}
 \text{(b)} \quad & \frac{d^2 \underline{R}}{dt^2} = \\
 &= \frac{d}{dt} \left(\frac{d \underline{R}}{dt} \right) = \frac{d}{dt}(-3 \sin t) \underline{i} + \frac{d}{dt}(3 \cos t) \underline{j} + \frac{d}{dt}(4) \underline{k} \\
 &= (-3 \cos t) \underline{i} + (-3 \sin t) \underline{j} \\
 &= (-3 \cos t) \underline{i} - (3 \sin t) \underline{j}
 \end{aligned}$$

Example 7 (a)-(d)

$$\begin{aligned}
 (c) \left\| \frac{d\underline{R}}{dt} \right\| &= \sqrt{(-3 \sin t)^2 + (3 \cos t)^2 + 4^2} \\
 &= \sqrt{9 \sin^2 t + 9 \cos^2 t + 16} = \sqrt{25} = 5
 \end{aligned}$$

$$\begin{aligned}
 (d) \left\| \frac{d^2\underline{R}}{dt^2} \right\| &= \sqrt{(-3 \cos t)^2 + (-3 \sin t)^2 + 0^2} \\
 &= \sqrt{9(\sin^2 t + \cos^2 t)} = \sqrt{9} = 3
 \end{aligned}$$

Example 8

Suppose \underline{A} has constant magnitude. Show that $\underline{A} \cdot \frac{\underline{dA}}{dt} = 0$ and that \underline{A} and $\frac{\underline{dA}}{dt}$ are perpendicular provided $\left\| \frac{\underline{dA}}{dt} \right\| \neq 0$.

$$\begin{aligned}\frac{d}{dt} (\underline{A} \cdot \underline{A}) &= \underline{A} \cdot \frac{\underline{dA}}{dt} + \frac{\underline{dA}}{dt} \cdot \underline{A} \\ &= 2\underline{A} \cdot \frac{\underline{dA}}{dt} = 0\end{aligned}$$

Thus, $\underline{A} \cdot \frac{\underline{dA}}{dt} = 0$ and \underline{A} is perpendicular to $\frac{\underline{dA}}{dt}$ provided $\left\| \frac{\underline{dA}}{dt} \right\| \neq 0$.

Example 9

Suppose $\underline{p} = 3t \underline{i} - t^2 \underline{j}$ and $\underline{q} = 2t^2 \underline{i} + 3\underline{j}$. Verify the result $\frac{d}{dt}(\underline{p} \cdot \underline{q}) = \underline{p} \cdot \frac{d\underline{q}}{du} + \frac{d\underline{p}}{du} \cdot \underline{q}$

Solution:

$$\underline{p} \cdot \underline{q} = (3t)(2t^2) - (3t^2) = 6t^3 - 3t^2$$

$$\frac{d}{dt}(\underline{p} \cdot \underline{q}) = 18t^2 - 6t$$

Example 9

$$\frac{d\underline{p}}{du} = 3\underline{i} - 2t\underline{j} \quad \frac{d\underline{q}}{du} = 4t \underline{i}$$

$$\underline{p} \cdot \frac{d\underline{q}}{du} + \frac{d\underline{p}}{du} \cdot \underline{q} = (3t \underline{i} - t^2 \underline{j}) \cdot (4t \underline{i}) + (3\underline{i} - 2t\underline{j}) \cdot (2t^2 \underline{i} + 3\underline{j})$$

$$= 12t^2 + 6t^2 - 6t$$

$$= 18t^2 - 6t$$

We have verified $\frac{d}{dt}(\underline{p} \cdot \underline{q}) = \underline{p} \cdot \frac{d\underline{q}}{du} + \frac{d\underline{p}}{du} \cdot \underline{q}$

Example 10

If $\underline{r}(t) = 4t^2 \underline{i} + 2t \underline{j} - 7 \underline{k}$, evaluate $\underline{r}(t)$ and $\underline{r}'(t)$ when $t = 1$.

$$\begin{aligned}\underline{r}(t) &= 4(1)^2 \underline{i} + 2(1)\underline{j} - 7 \underline{k} \\ &= 4\underline{i} + 2\underline{j} - 7\underline{k}\end{aligned}$$

$$\begin{aligned}\underline{r}'(t) &= 8t \underline{i} + 2 \underline{j} = 8(1) \underline{i} + 2 \underline{j} \\ &= 8\underline{i} + 2\underline{j}\end{aligned}$$

Thank You